REFERENCES

1. J. Blake and H.B. Gurocak. 2009. Haptic Glove With MR Brakes for Virtual Reality. *Mechatronics, IEEE/ASME Transactions on* 14, 5 (Oct 2009), 606–615. DOI: http://dx.doi.org/10.1109/TMECH.2008.2010934
2. M. Bouzit, G. Burdea, G. Popescu, and R. Boian. 2002. The Rutgers Master II-new design force-feedback glove. *Mechatronics, IEEE/ASME Transactions on* 7, 2 (Jun 2002), 256–263. DOI: http://dx.doi.org/10.1109/TMECH.2002.1011262
3. T. Endo, H. Kawasaki, T. Mouri, Y. Doi, T. Yoshida, Y. Ishigure, H. Shimomura, M. Matsumura, and K. Koketsu. 2009. Five-fingered haptic interface robot: HIRO III. In *EuroHaptics conference, 2009 and Symposium on Haptic Interfaces for Virtual Environment and Teleoperator Systems. World Haptics 2009. Third Joint*. 458–463. DOI: http://dx.doi.org/10.1109/WHC.2009.4810812
4. Brent Edward Insko. 2001. *Passive Haptics Significantly Enhances Virtual Environments*. Ph.D. Dissertation. University of North Carolina at Chapel Hill. http://www.cs.unc.edu/techreports/01-017.pdf
5. T. Koyama, I. Yamano, K. Takemura, and T. Maeno. 2002. Multi-fingered exoskeleton haptic device using passive force feedback for dexterous teleoperation. In *Intelligent Robots and Systems, 2002. IEEE/RSJ International Conference on*, Vol. 3. 2905–2910 vol.3. DOI:http://dx.doi.org/10.1109/IRDS.2002.1041713
6. Zhou Ma and P. Ben-Tzvi. 2015. RML Glove;An Exoskeleton Glove Mechanism With Haptics Feedback. *Mechatronics, IEEE/ASME Transactions on* 20, 2 (April 2015), 641–652. DOI: http://dx.doi.org/10.1109/TMECH.2014.2305842
7. T. H. MASSIE. 1994. The PHANToM Haptic Interface : A Device for Probing Virtual Objects. *Proceedings of the ASME Winter Annual Meeting, Symposium on Haptic Interfaces for Virtual Environment and Teleoperator Systems, Chicago, IL, Nov., 1994* (1994). http://ci.nii.ac.jp/naid/10018008840/en/
8. Katsunari Sato, Kouta Minamizawa, Naoki Kawakami, and Susumu Tachi. 2007. Haptic Telexistence. In *ACM SIGGRAPH 2007 Emerging Technologies (SIGGRAPH '07)*. ACM, New York, NY, USA, Article 10. DOI: http://dx.doi.org/10.1145/1278280.1278291
9. Cyberglove Systems. 2015. Hand Motion Capturing and Force Feedback with Cybergrasp. (2015). http://www.cyberglovesystems.com/ [Online; accessed 25-September-2015].